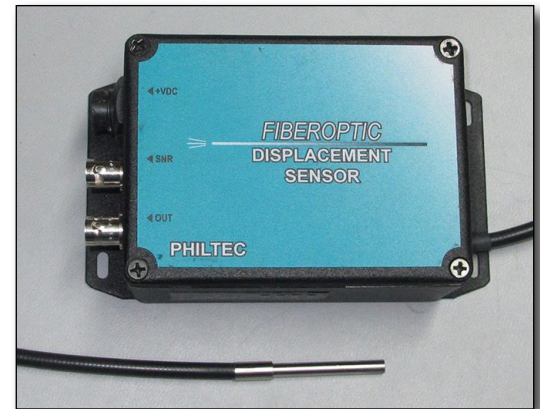


Fiberoptic Sensor - Reflectance Compensated*

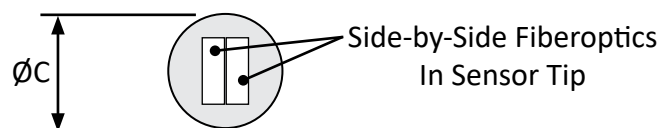
Model RC63



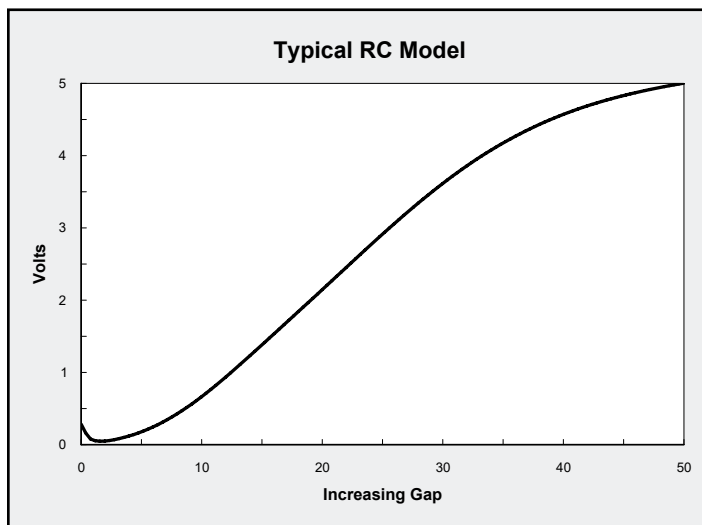
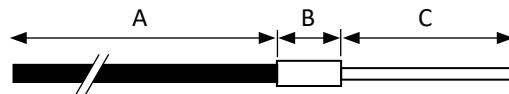
For The Measurement of Distance, Displacement and Vibration
for Targets > \varnothing 3.6 mm

Features

- Reflectance Compensated Output
- 4 mm Operating Range
- 1.6 x 3.2 mm Spot Size
- 1.8 mv/ μ m Sensitivity (46 mv/mil)



Tip & Cable Dimensions



| FEATURE | mm | inch |
|-------------------------------------|----------------|------------------|
| Tip Outer Diameter, $\varnothing C$ | 4.75 | 0.187 |
| Fiberoptic Area | 1.58 x 3.18 | 0.063 x 0.125 |
| Tip Length, C | 38.1 | 1.5 |
| Collar Length, B | 12.7 | 0.500 |
| Collar Diameter, $\varnothing B$ | 6.35 | 0.250 |
| Cable Length, A | 915 | 36 |
| Cable Diameter, $\varnothing A$ | 5.97 | 0.235 |
| Cable Min. Bend Radius | 22 | 0.875 |

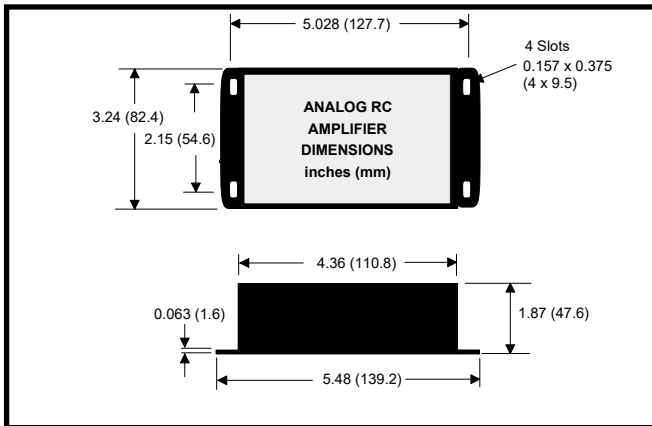
*These are reflective type transducers based upon detecting the intensity of reflected light. RC Model sensors have a pair of adjacent fiberoptic detectors in the sensor tip. Light reflected off the target follows two separate paths back to the electronics where a ratiometric calculation provides the distance measurement which is independent of varying surface reflectance; i.e., *reflectance compensated*.

Analog sensors are fast responding units ideal for process control and vibration measurements in dynamic applications:

- DC-20 KHz bandwidth is standard
- DC-200 KHz or higher (up to 350 KHz) is optional
- DC-100 Hz providing best resolution, is optional

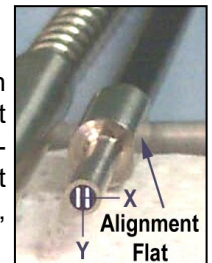


Standard single channel units include amplifier and sensor tip with 914 mm long (3 foot) fiberoptic cable, require +12 VDC input power, and provide 0 to +5 volt analog output with DC - 20 KHz bandwidth.



SENSOR TIP ALIGNMENT

RC sensors have adjacent fiber bundles in the face of the sensor. An alignment flat is provided on the casing to aid with alignment. The flat is ground parallel to the split between the adjacent fiberoptic bundles, and located on the light transmitting side.



| Standard Specifications - RC63 | | | | | | |
|--------------------------------|------------------------|---------------------------|--|---------------------------|-----------|-----------|
| Electronics | | Fiberoptics | | Analog Output (0-5 Volts) | | |
| Light Source | LED, 880 nm | Light Beam Spread | 30° | Total Range | 0.160 in. | 4 mm |
| Input Voltage | +12 VDC | Tip Material | 300 Series SS | Linear Range* | 0.050 in. | 1.2 mm |
| Input Current | 125 ma max | Tip Epoxy Outgas | 0.3% @ 200°C 2.4% @ 300°C | Nominal Standoff* | 0.054 in. | 1.4 mm |
| Bandwidth | DC-20 KHz 3 db down | Tip Operating Pressure | 15 bar | Nominal Sensitivity* | 46 mv/mil | 1.8 mv/μm |
| Iso-thermal Drift | 0.5% | Tip Operating Temperature | -55 to 200°C continuous; to 300°C intermittent 1-2 hours | Resolution** | 160 μin | 4 μm |
| Operating Temperature | 0 to 70°C | Cable Jacket | PVC over Steel Monocoil | | 80 μin | 2 μm |
| Weight | 0.7 kg -1.5 lbs. | | 10 to 107°C | | 28 μin | 0.7 μm |

NOTE: Nominal Standoff = the gap distance that places the sensor at the middle of the linear operating range.

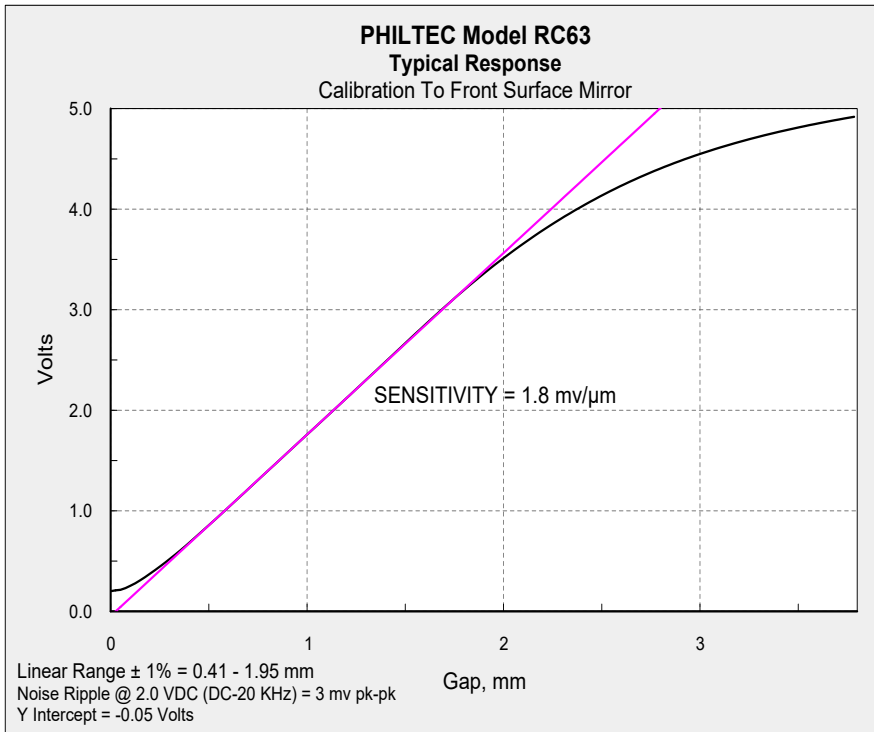
*Standard Specifications provide nominal values only. Actual production values may vary by as much as ±15%.

**These specifications represent best case performance where:
 the target is flat, smooth and highly reflective,
 the sensor is perpendicular to the target,
 the sensor is gapped to its range of highest sensitivity,
 fiberoptic cable lengths are standard and the cable is not connectorized.

CONVERTING THE ANALOG OUTPUT TO DISTANCE

A calibration chart is provided with each sensor giving the voltage output response to distance. There are three ways to derive accurate distance measurements:

- within the bounds of the linear range, convert the change in voltage output as follows:
Distance = Δ milliVolts \div Sensitivity = μm
- over the non-linear range, create a lookup table using the XY calibration data points, or
- use a polynomial curve fit to accurately map the sensor's output function



FACTORY CALIBRATION

A factory supplied calibration chart provides:

- Sensor model & serial number
- Date of calibration
- The linear sensing range
- The slope sensitivity
- The y intercept of the linear range
- The AC noise ripple

The XY calibration data points are made available upon request.

FREQUENCY RESPONSE

The standard 20 KHz RC sensor has a 2-pole but-terworth frequency rolloff. The chart here shows that typical response. With the 3 db down point set at 20 KHz, the output is flat out to approximately 6 KHz.

With a high frequency amplifier, the 3 db down point is set at 200 KHz or higher (up to 350 Hz).

With a low frequency amplifier, the 3 db down point is set at 100 Hz.

